

Design Optimization of NEM Switch Fabricated in Standard 65nm CMOS Back-End-of-Line Process

Mariana Martinez*, Urmita Sikder¹, Kimihiko Kato¹, and Tsu-Jae King Liu¹

* Department of EECS, UT El Paso, ¹ Department of EECS, UC Berkeley

Abstract

The design of a single-pole/double-throw (SPDT) nano-electro mechanical (NEM) switch implemented using the metal interconnect layers available in a standard 65 nm CMOS back-end-of-line (BEOL) process is investigated for non-volatile NEM memory (NEMory) applications. The Coventorware MEMS+ finite element analysis (FEA) software tool is used to study design trade-offs. The device geometry and dimensions are optimized to minimize the switching energy, mechanical delay and settling time.

Introduction

Hybrid CMOS/NEM technology recently has been proposed to enable faster and more energy-efficient data searching as compared with CMOS technology [1]. This work investigates the design of a non-volatile SPDT NEM switch implemented using a standard 65 nm CMOS BEOL process, to elucidate trade-offs between performance and energy efficiency.

NEMory Cell Design

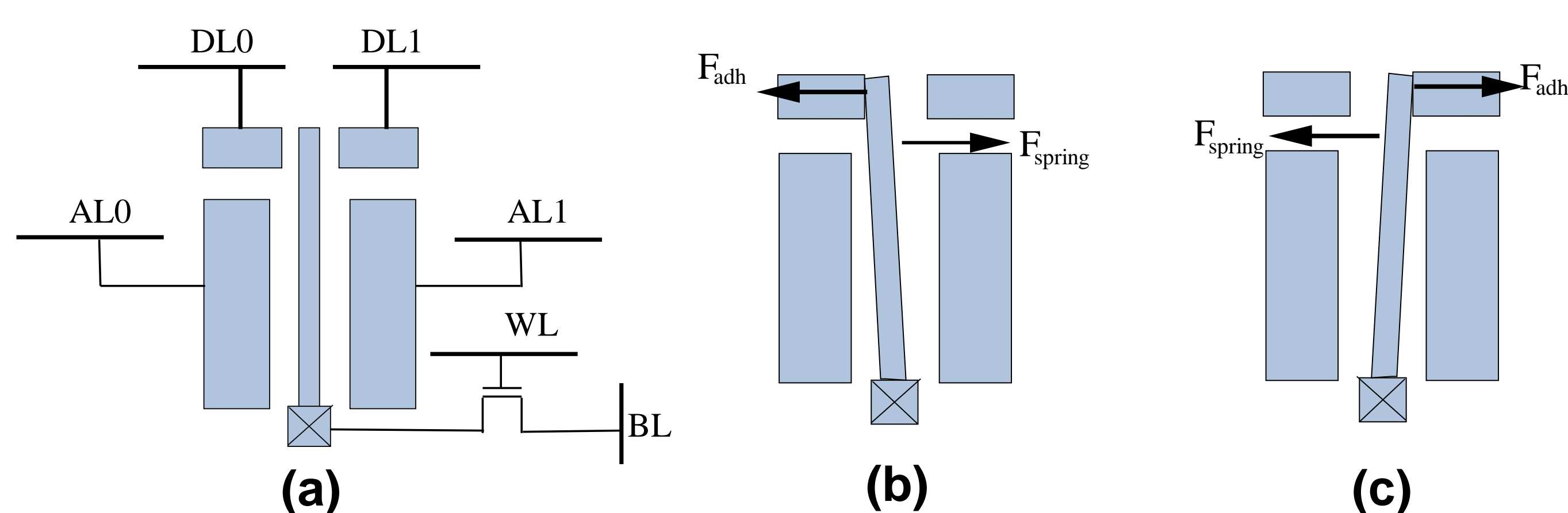


Fig. 1: (a) NEMory cell structure (b) NEM switch in "0" state (c) NEM switch in "1" state

- NEMory cell comprises a vertically oriented beam, programmed to touch either data line: DL0 ("0" state) or DL1 ("1" state)
- To program the cell, a voltage (V_{prog}) is applied to either AL0 or AL1, bit line (BL) is pulsed low, and word line (WL) is pulsed high.

- By implementing the NEM switch in BEOL layers, low-cost integration with CMOS and small cell area (footprint) can be achieved.
- In this work, multiple 1X metal layers, with minimum feature size and spacing of 100 nm, are used to implement the NEM switch.
- The vertically oriented beam is released by anisotropic and isotropic etching of the surrounding inter-metal dielectric material.

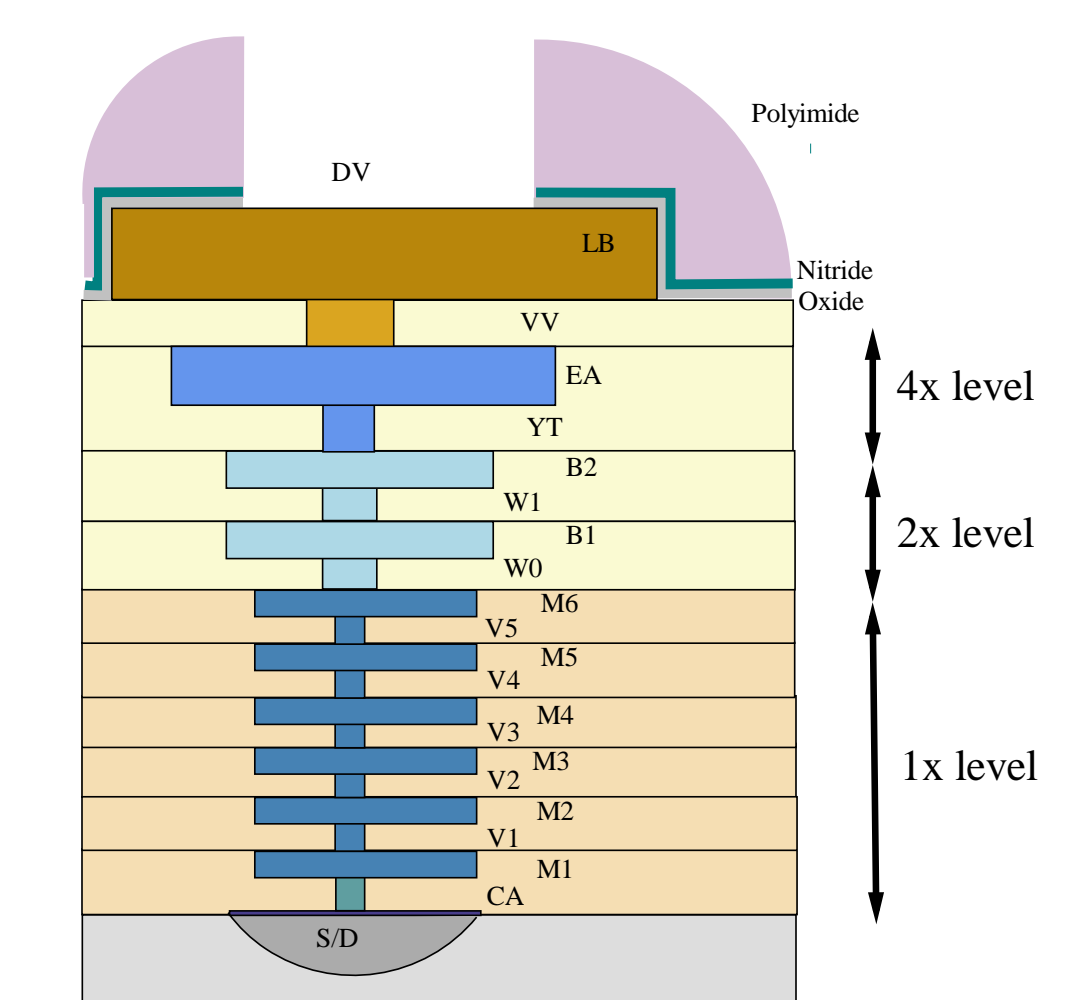


Fig. 2: Schematic cross-section of BEOL layers in 65 nm CMOS process

BEOL NEM Switch Design Trade-Offs

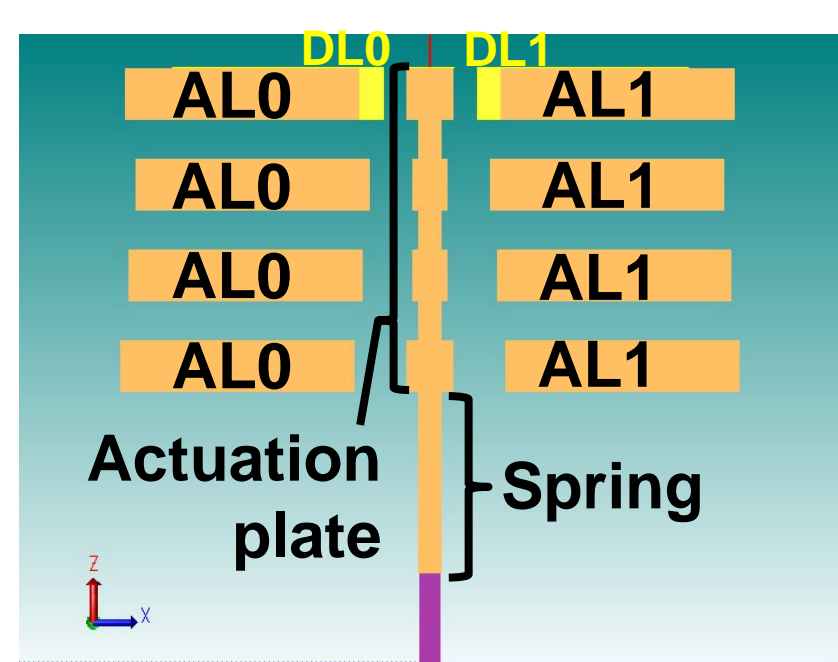


Fig. 3: Cross-sectional view of simulated SPDT NEM switch structure, from MEMS+

- Reduction in spring stiffness provides for lower pull-in voltage (V_{PI}), but increases the likelihood of catastrophic pull-in to AL0/AL1.
- The actuation plate should be stiffer to reduce the possibility of catastrophic pull-in, but this increases the mass, resulting in slower switching speed.
- A larger actuation gap for the bottom AL layers results in reduced oscillation upon contact, but at the trade-off of increased V_{PI} .

Design Optimization Approach

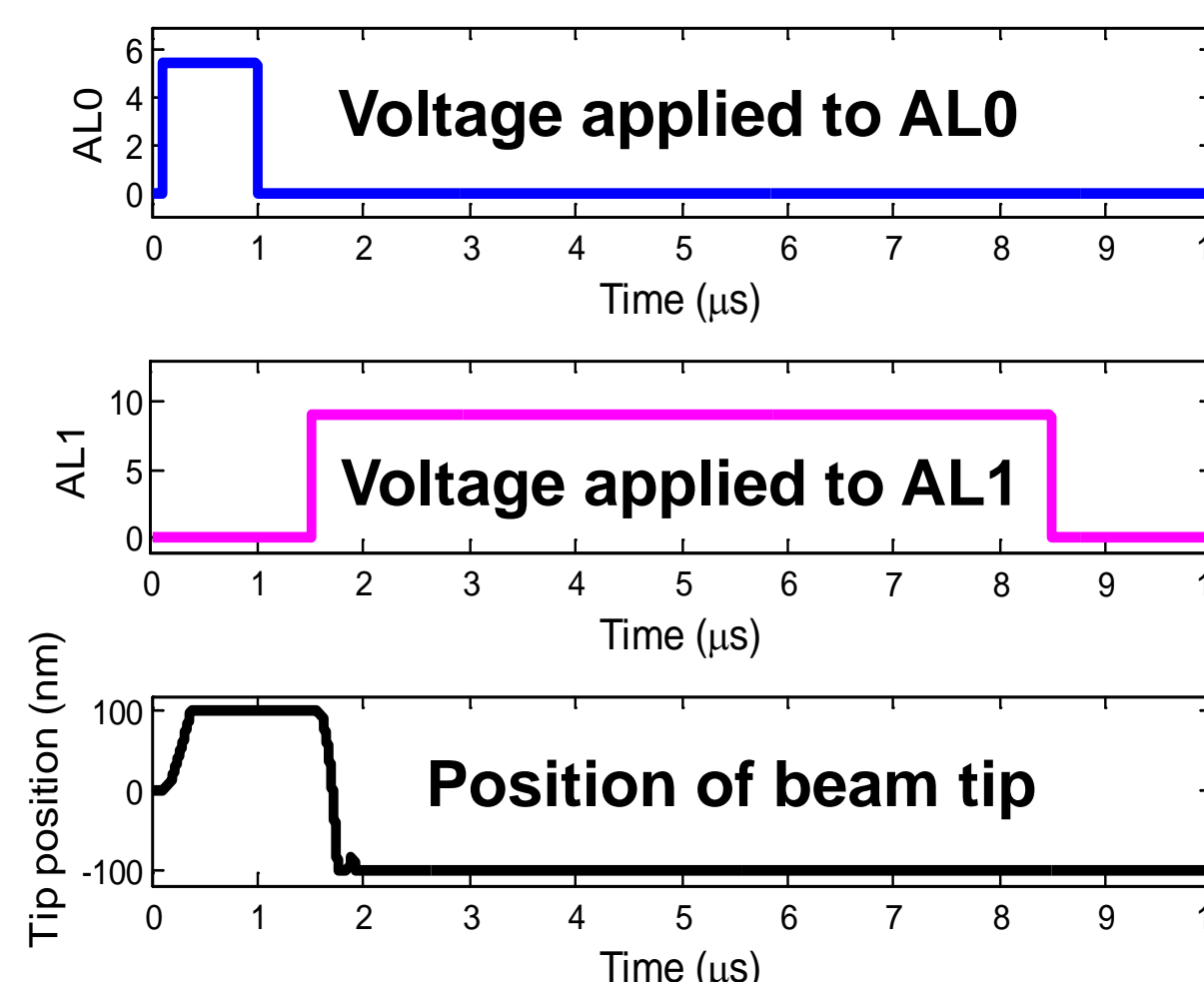


Fig. 4: Transient simulation waveforms of cell programming and reprogramming operations.

Parameter	Values
Stiffness, k_{eff}	0.37 N/m
Contact gap, g_d	100 nm
Contact area	100 nm × 220 nm
Actuation area	20 μ m × 220 nm
Actuation gap, g_0	180 to 250 nm
Adhesive force, F_{adh}	45 nN
$V_{PI,program}$	5.5 V
$V_{PI,reprogram}$	9.0 V

- For non-volatile operation, contact adhesive force (F_{adh}) must be greater than the beam's spring restoring force (F_{spring}).
- For reprogramming capability, the electrostatic force (F_{elec}) must be greater than $F_{adh} - F_{spring}$. To minimize F_{elec} and hence the switching energy, $F_{spring} \cong F_{adh}$.
- To reduce the possibility of catastrophic pull-in:
 - Add vias between actuation plate layers to reduce torsional motion
 - Make actuation plate thicker in M3 and M6 layers

Results and Discussion

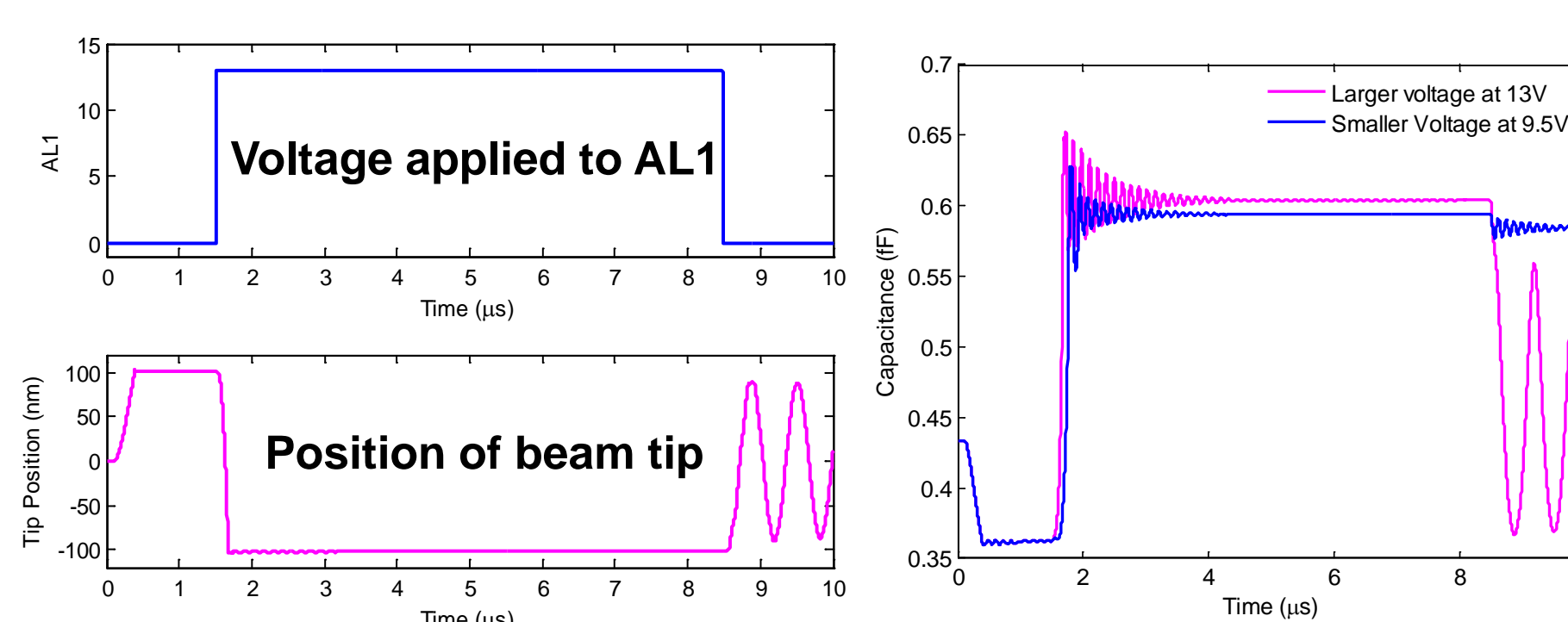


Fig. 5: Transient simulations of cell reprogramming failure.

- Beam oscillation must cease before V_{prog} is removed for successful reprogramming.
- Larger overdrive (higher contact velocity) results in stronger oscillation.

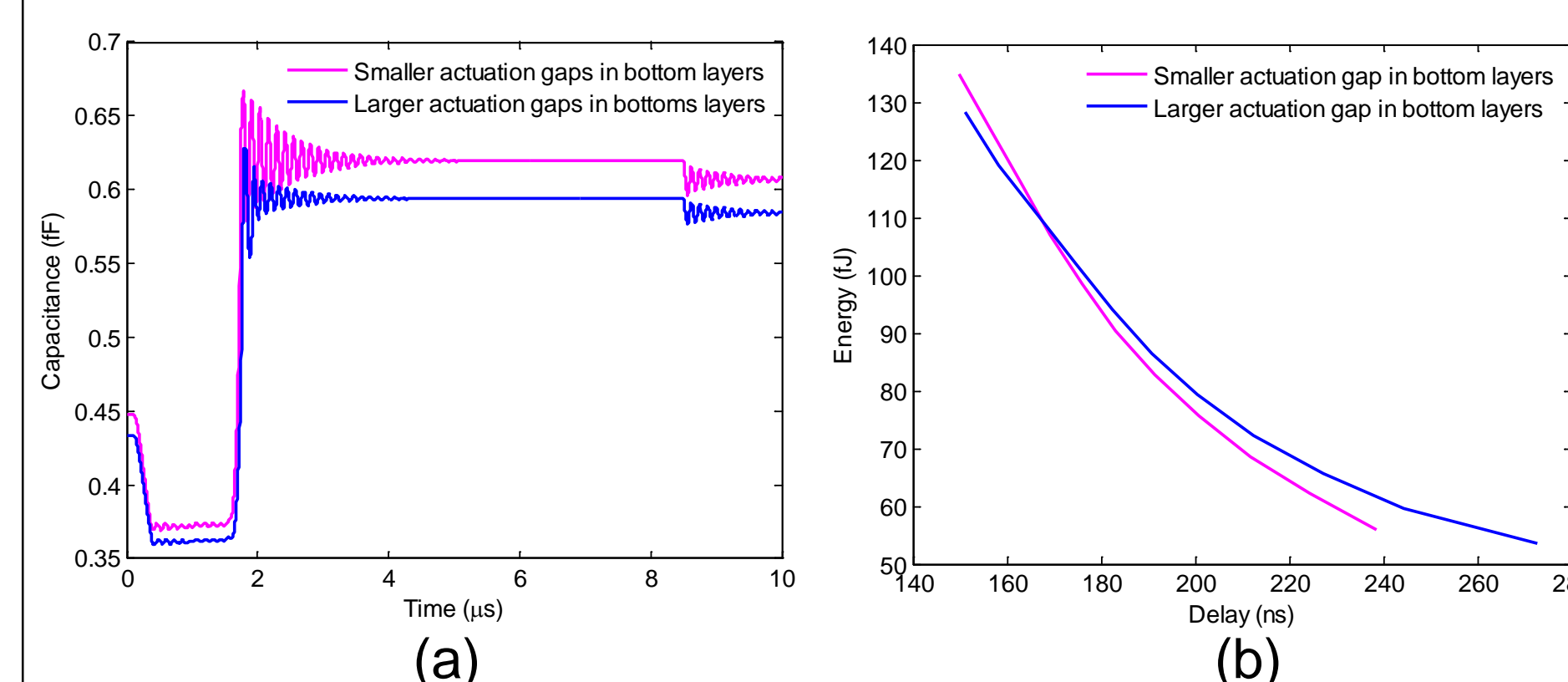


Fig. 6: Effects of bottom actuation gap size: (a) transient beam capacitance for $V_{prog} = 9.5$ V, (b) energy vs. delay.

- To reduce oscillation upon contact:
 - Make actuation plate narrower in M4 and M5 layers
 - Use larger actuation gaps at bottom (M3)

→ Energy × delay product increases.

Summary

- Design guidelines for SPDT NEM switch design to achieve non-volatile operation with minimum energy × delay are developed.
- A stiffer actuation plate is advantageous for avoiding catastrophic pull-in, at a tradeoff of longer switching delay.

Reference:

[1] K. Kato *et al.*, "Non-Volatile Nano-Electro-Mechanical Memory for Energy-Efficient Data Searching," *IEEE Electron Device Letters*, vol. 37, no. 1, pp. 31-34, 2016.

Contact Information

* mmartinez63@miners.utep.edu

Support Information

This work was funded by National Science Foundation EECS 0939514

